

Hard- und Software Burkhard Lewetz

Technical Software Engineering

How does it work... ... with *WinPC-NC* ?

Setting up the automatic tool changer (ATC)

Light

✓ USB

✓ Professional



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In this manual you will learn how to set up an automatic tool changer with *WinPC-NC* and how to realise the changing process.

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Checklist for tools and materials

Tools and equipment needed:

- ✓ 3- or 4-axis CNC milling machine
- ✓ Spindle motor with controllable tool holder / collet chuck
- ✓ Tool magazine with up to 30 positions
- ✓ WinPC-NC USB or WinPC-NC Professional software as of version V3 or V4



Note:

Before starting, please make sure that all the above requirements are fulfilled in order to complete the project successfully.

Please read these instructions completely first and only then start with the project.

Additional and extended functions with WinPC-NC- Professional :

Compared to *WinPC-NC USB*, *WinPC-NC Professional* offers additional functions and monitoring or setting options for automatic tool change.

- Monitoring of the magazine positions with a sensor to prevent placement in already occupied holders
- Monitoring of the molette with a sensor to detect if a tool has been picked up correctly
- ✓ Additional measurements of the tools at the length sensor after grab and before release to detect tool breakage and correct tool handling, output of corresponding error messages and possibility of correction and subsequent further processing
- ✓ Definition of critical and protected area in the machine room, which is constantly monitored and accidental overrun is prevented. This makes it easy to protect and monitor the magazine area.



Introduction: Automatic tool change in *WinPC-NC*

In *WinPC-NC* is it possible to realise an automatic tool change.

With the help of these functions, milling jobs with more than one tool can be fully automated.

The extensive options for automatic tool change allow up to 30 different tools to be picked up from a magazine and automatically put away again after use.

It is possible to use both a linear tool magazine (tool rack) and axial designs using the 4th axis, e.g. a turret magazine.

In this manual we would like to give you an overview of which functions are available and how you can available and how you can set them up on your machine.



Fundamentals:

In order to be able to use the automatic tool change in *WinPC-NC*, we would first like to give you a general overview of the individual functions and processes that are used here.

Due to the enormous flexibility of the possible tool positions and magazine variants, commissioning takes place in two steps.

First, the settings in the **changer magazine** are used to specify the positions of the individual tools in front **of** or **above** the actual tool magazine.

Then the sequence for **picking up** and **placing** the tools is programmed using the macro functions. This procedure allows very flexible sequences to be programmed and also various additional signals, such as **collet open** or **taper cleaning**, to be controlled individually.

On the following pages, we would like to provide you with step-by-step instructions for putting the automatic tool change into operation on your machine.





Step 1: Activate the option for automatic tool change

Activate the automatic tool changer in **Parameter-Basic Settings-Equipment** and, if required, also with 4th axis.

Coordinates	Tools N	lisc. param	eters Tech	nology Ma	acro Import Fo	ormats <u>Basic Se</u>	ttings			
	Speed	l control			Monitori	ng		Disp	olay/Operation	
Ports	X-Axis	Y-Axis	Z-Axis	4.Axis	Equipment	Dimensions	Homing	Jog	Signal Wizard	Spindle
 Technology Cylindrical axis Tangentional cutting Dispensing Oxy/fuel cutting 3D Printing Laser 						Automati		er (ATC)	6	

Activate the option **Change tools = Yes, use ATC** in **Parameter-Misc.** under the **Job execution** tab.

Parameters				
Coordinates Tools Misc. parameters Technology Macro Import f	Formats Basic Settings			
Display/Operation Job execution				
Start/endposition	Automatic homing at job start			
stop	Z dipping			
Change tools	Enable resume job			
Yes, use ATC •				
\mathbf{k}				
-Dwell times	Jobstart			
Dwell time after Z up (ms)0	Advance 100 %			

Then save the new settings with **Save....**

To configure an automatic tool change using the 4th axis, please also activate the options **Tool changer with 4th axis** and **4th axis**.



Step 2: Set the magazine positions

To be able to set the positions of the individual tools, open the **Parameter-Tools** menu and **s**elect the **ATC magazine** tab here:

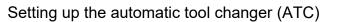
Activation	Speeds	Dimensions	ATC magazine					
Activation	ppeeus							
		X	Y		Z			ATC
1	+	_50.00	+500.00	+_	0.00			
2	+1	100.00	+500.00	+	0.00			
3	+	150.00	+500.00	+	0.00			
4	+2	200.00	+500.00	+	0.00			
5	+2	250.00	+500.00	+	0.00			
6	+3	300.00	+500.00	+	0.00		No Z lift at ATC	
7	+(350.00	+500.00	+	0.00	Ν	 No move back to last pos. Length check after grab 	
8	+	_0.00	+0.00	+	0.00	6	Release length check	
9	+	_0.00	+0.00	+	0.00		Length check after release	
10	+	_0.00	+0.00	+	0.00			

In the dialog above it is possible to enter the positions of the individual tool magazine holders.

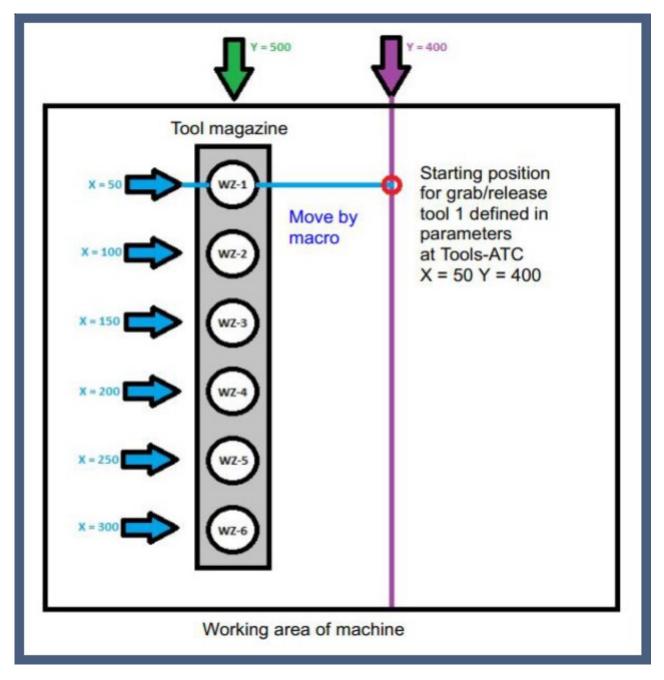
When entering the tool positions, please note that **only the position in front of or above the tool magazine** should be entered. The procedures for moving to the final position are then set up using macros.

The following graphic illustrates this procedure again. In our example, **tool 1** is in the magazine at position X = 50 and Y = 500.

Since the tool is to be inserted into the tool holder from the front, we define the magazine position to be approached as X = 50 and Y = 400.







When the positions for all tools have been determined and entered, the settings can be saved using **Save...**

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Example: Positions from the graphic shown above:

Activation 5	X +50.00 +100.00 +150.00 +250.00 +300.00 +350.00 +0.00 +0.00 +0.00	ATC magazine Y +500.00 +500.00 +500.00 +500.00 +500.00 +500.00 +500.00 +0.00 +0.00 +0.00	Z +0.00 +0.00 +0.00 +0.00 +0.00 +0.00 +0.00 +0.00 +0.00 +0.00	<u></u>	ATC No Z lift at ATC No move back to last pos. Length check after grab Release length check Length check after release
				_	



Note:

If there are fewer magazine positions in your tool magazine than would be possible in *WinPC-NC*, leave the position specifications at 0 in each case.

Please note that the tools may then not be called up in the milling job!



Step 3: Grab and release tools using macros

To move from the **start positions** in the parameters to the actual **changer magazine positions**, it is necessary to move these sequences using the macro functions.

The macros are also used to control the additional signals such as collet chuck or taper cleaning.



Note:

It is not possible or intended to use the automatic tool changer without the macro programming.

The macro programming is done in the parameter dialog under the tab **Macro**. You should now see this menu displayed:

session start session end		
job start	Delete	Current macro
job end before homing after homing	Insert	
before PEN DOWN after PEN DOWN before PEN UP	Replace	
after PEN UP before tool change after tool change ATC release	Append	
ATC release ATC grab		
Macros <u>R</u> eload	0	New macro command Macro commands
 Disable macros No automatic outputs 		Wait
Macro Jobend if canceled		ResetOutput Speed





Basics of macro programming:

The macro functions in *WinPC-NC* are a very extensive and powerful tool for realising automatic processes. Because of the many possibilities that result from this, we would first like to go into the basics.

session start						
session end		Delet	e	Cur	rent macro	
job start job end				Mo	veY 100.000	
before homing		Inser	t	-		
after homing						
before PEN DOWN		Repla	ce			
after PEN DOWN before PEN UP	- 81					
after PEN UP		Apper	d			
before tool change		Apper	iu			
after tool change	_					
ATC release						
ATC grab	-	M	oveY		New macro command	
					New macro command	
Macros <u>R</u> eload		+_100.000	Y	Macro co	mmands	
				ResetOu	tput	
Disable macros				Speed		
				MoveX MoveY		
No automatic outputs				MoveZ		
Macro Jobend if canceled				MoveXY		

In general, the macro menu is divided into two areas:

On the left side you will find the so-called entry points for the macros:

Execute macro at	
session start session end job start job end before homing after homing before PEN DOWN after PEN DOWN before PEN UP after PEN UP before tool change after tool change	
ATC release ATC grab	7



The entry points **ATC release** and **ATC grab** are relevant for the additional traverses and processes during the tool change.

To select an entry point, click on it until it is highlighted in blue.

On the right-hand side of the menu, you will find the editor for programming the sequence of the individual macro commands:

Delete	Current macro
Insert	MoveY 100.000
Replace	
Append	
Wait	New macro command
0	Macro commands
	Wait WaitInputHigh WaitInputLow SetOutput ResetOutput

The new sequence is programmed or displayed in the upper part under Current macro.

The individual functions or macro commands can be selected further below. After the selection, it is possible to set further parameters for the selected command.



For example, to insert a macro command that moves the X axis by +100, the following settings should be made:

Delete	Current macro
Insert	MoveX 100.000
Replace	
Append	
MoveX	New macro command
MoveX +_100.000 X	New macro command Macro commands ResetOutput Speed MoveX

To do this, first select the macro command and then set the parameter for the move to be executed. With a click on **Insert** or **Append** this command is now taken over into the current macro list.

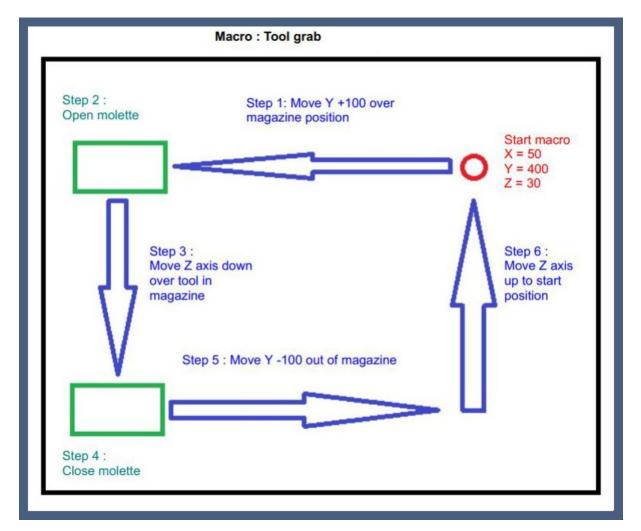
In order to use macros to program the picking up (grab) and putting down (release) of the tools, it is necessary to create a sequence of several macro commands.

For an overview of the travel paths and additional signals, it is useful to make a simple sketch.

In our example, a linear tool magazine is to be used (tool shelf). The tool is to be inserted into the clamping holder of the magazine via the Y-axis.



The necessary travel paths for picking up (grab) a tool are as follows:



- **Step 1:** Moving from the start position specified in the ATC parameters to position over tool holder
- **Step 2:** Open the molette and switch on taper cleaning
- **Step 3:** Move the spindle down over the tool holder
- **Step 4:** Close the mollette and switch off the taper cleaning
- **Step 5:** Moving out of the tool magazine with Y axis
- **Step 6:** Raise Z-axis to original start position





In order to be able to program this sequence using macros you must implement the individual steps accordingly.

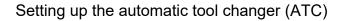
The complete sequence should then look similar to this one:

Delete	Current macro			
Insert	MoveY 100.000 CleaningOn MoletteOpen			
Replace	MoveZ -70.000 CleaningOff MoletteClose MoveY -100.000 MoveZ 70.000			
Append				
MoveZ +70.000 z	New macro command Macro commands			
	MoveY MoveZ MoveXY MoveYZ MoveYZ			



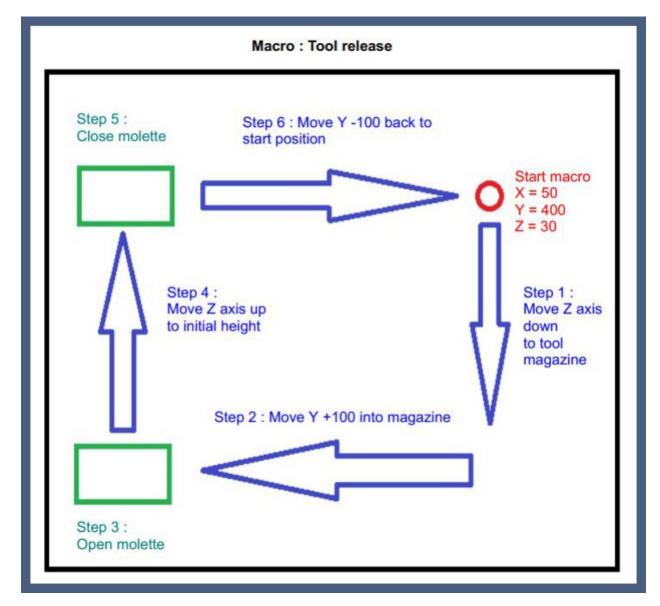
Note:

The signals for the molette (collet chuck) and the magazine blow-out (taper cleaning) are available in the signal wizard and must be assigned the pin numbers of the interface that are electrically wired. The output signals Q248 and Q245 are relevant for molette and taper cleaning.





The sequence for releasing the tool is now programmed in the same way. The movement sequence for placing the tool down looks something like this:





For our example, the release macro looks as follows:

Delete	Current macro
Insert	MoveZ -70.000 MoveY 100.000 CleaningOn
Replace	MoletteOpen MoveZ 70.000 CleaningOff
Append	MoletteClose MoveY -100.000
MoveY	New macro command
100.000 Y	Macro commands MoveY MoveZ MoveXY MoveXZ MoveYZ MoveYZ MoveXY7

In principle the steps are exactly the same as in the procedure for grabbing the tool but has inverted sequence and the molette must be opened first.

If you want to control your tool changer by means of the **4th axis**, the procedure with the macros is the same, only a path for the 4th axis is defined for the magazine positions, e.g. to extend a drawer or to rotate a turret magazine.

In this case the tool table contains a fourth column under **Parameter-Tools-ATC** in which the positions of the 4th axis can be entered.

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arameters Coordinates Tools Misc. parameters Technology Macro Import Formats Basic Settings Activation Speeds Dimensions ATC magazine Υ z 4 х ATC +___50.00 +__500.00 0.00 0.00 + + 1 +__100.00 + 0.00 0.00 +__500.00 2 +__150.00 +__500.00 + 0.00 0.00 + 3 R + 200.00 0.00 0.00 +__500.00 + 4 +___250.00 +__500.00 0.00 0.00 + + 5 +__300.00 0.00 0.00 No Z lift at ATC +__500.00 + + 6 No move back to last pos. +__350.00 +__500.00 0.00 0.00 +_ +_ 7 Length check after grab +___0.00 0.00 0.00 +___0.00 + + 8 Release length check 0.00 0.00 0.00 0.00 +_ + +_ +_ Length check after release 9 0.00 0.00 0.00 0.00 +___ + + +___ 10

If movements of the 4th axis are necessary for release and grab tools, there are also macro commands for this and the 4th axis can be moved in the same way as the three axes XYZ.

Move4			New macro command		ind
+12.500	4	Macro co	mmands	i	
		MoveXZ MoveYZ MoveXY			
		Move4		N	
		MoveAb		13	





Step 4: Test the new settings

If the configuration of the tool changer has been carried out, the new settings can now be tested. To do this, carry out a reference run in the first step and bring your machine into a ready-to-run state.

Now open the **Select tool** menu:

le	Move	Parameters	Special function	s Help			
-	Star	rt	F3		A		(3) /=
	Sta	rt <u>f</u> rom	Strg+F3			- 5	63 × 1
	Sta	rt single step					
	Zer	o point XY	F4				
	Par	k position	F9				
	log		F5				
	Joy	stick jogging					
		ialize the mac	hine F8				
	Sele	ect <u>t</u> ool	N				

A new dialog window opens with which you can control the tool changer manually:

Tool grab T	1 2	1	Werkzeug 1
2			Werkzeug 1
		2	
3			Werkzeug 2
	3	3	Werkzeug 3
4	4	4	Werkzeug 4
5	5	5	Werkzeug 5
6	6	6	Werkzeug 6
7	7	7	Werkzeug 7
8	8	8	Werkzeug 8
9	9	9	Werkzeug 9
10	10	10	Werkzeug 10
Release			STOP 🗸

If you click on the corresponding **tool number** in the **Grab** column, your machine carries out the automatic tool change with this tool.

First *WinPC-NC* reaches the defined magazine position and then executes all macro commands in the defined sequence. If all paths and times and sequences are defined correctly at the end the desired tool should be inserted in the molette and ready for further use.

To stop the process, you can abort the tool change and sequence at any time with **Stop**.

By clicking on **Release** the machine puts the tool down and stops in front of the magazine without a tool.

Select current tool		_	
Tool grab	Tools		
1	1	1	Werkzeug 1
2	2	2	Werkzeug 2
3	3	3	Werkzeug 3
4	4	4	Werkzeug 4
5	5	5	Werkzeug 5
6	6	6	Werkzeug 6
7	7	7	Werkzeug 7
8	8	8	Werkzeug 8
9	9	9	Werkzeug 9
10	10	10	Werkzeug 10
		_	
Rele	ase		STOP

Manual opening of the molette is possible with a click on the **molette button** in the lower menu bar.



Note:

Always test the new configuration carefully to prevent damage to your machine.

You can abort the tool change at any time by clicking Stop. If an unexpected malfunction occurs, you can also press the emergency stop button to cancel the process and all axis movements.





Note:

For the first tests, it is advisable to strongly limit the traversing speed during the tool change.

For this purpose, it is possible to select a safe and slow speed as the first step in the macro.

Speed		New macro command	
10.000	Macro co	mmands	
	ResetOut	tput	-
	Speed	N	
	MoveX	5	
	MoveY		- 1
	MoveZ		
	MoveXY		